

Modeling Infrastructure Degradation from Visual Inspections Using Network-Scale State-Space Models

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Motivation

- Developing a deterioration model for network-scale visual inspections.
- Estimating the deterioration rate from visual inspection data.
- Quantifying the uncertainty of visual inspections.

Contributions

The main contributions of this work are:

- **Model the deterioration** behaviour based on visual inspection data taken from a network of bridges.
- **Quantify the uncertainty of the inspectors** performing visual inspections.
- **Quantify inspections uncertainty** based on the deterioration state of the structural element and the inspectors uncertainty.
- **Validate and verify** the proposed methods with real and synthetic datasets respectively.

Visual Inspections Database

Information hierarchy for the data of a visual inspections system.

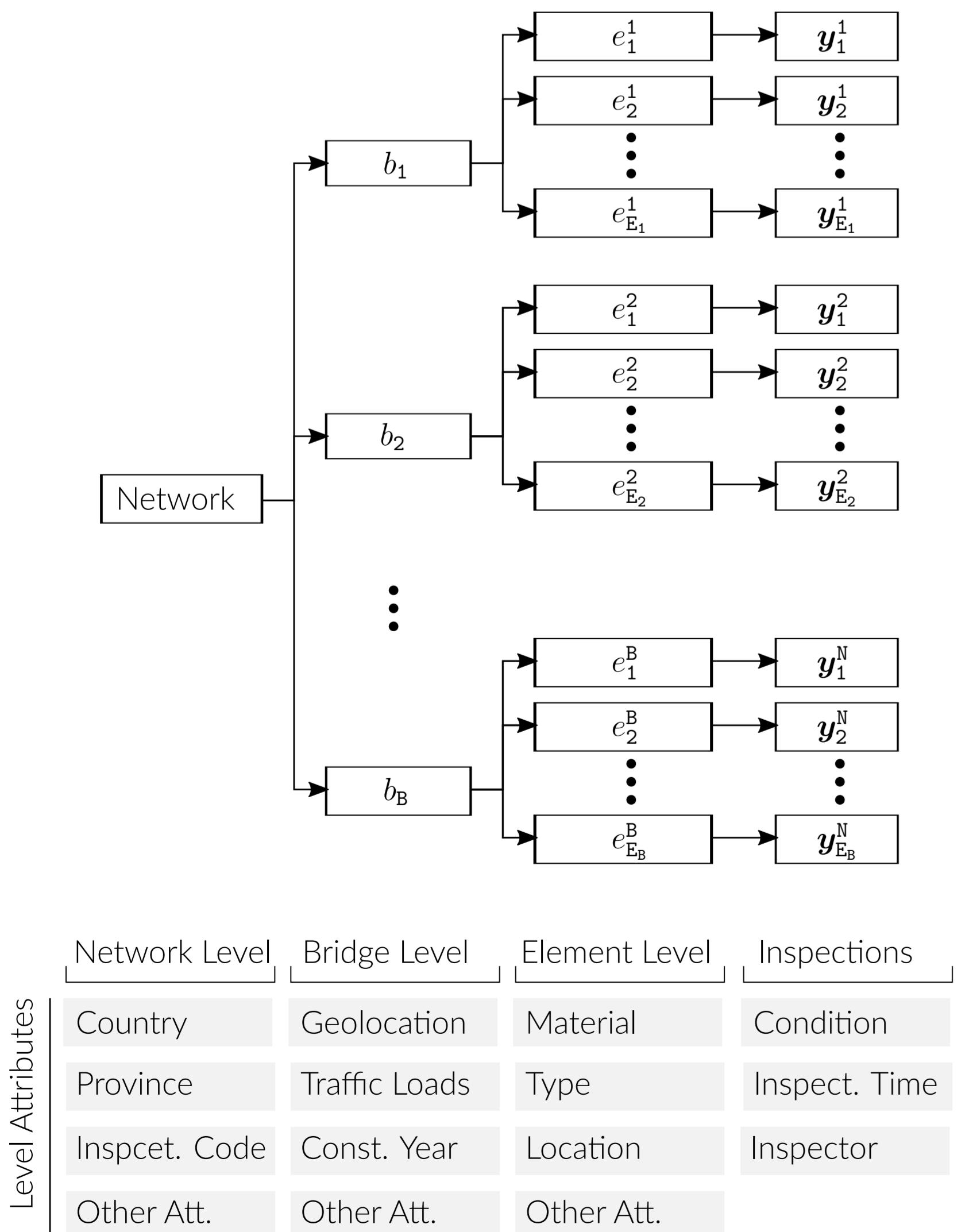


Figure 3. Information Hierarchy for Visual Inspection System

Deterioration Behaviour Described by Kinematics:

$$\begin{bmatrix} \dot{x}_t \\ \ddot{x}_t \\ \ddot{\dot{x}}_t \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & \Delta t & \frac{\Delta t^2}{2} \\ 0 & 1 & \Delta t \\ 0 & 0 & 1 \end{bmatrix}}_A \cdot \begin{bmatrix} x_{t-1} \\ \dot{x}_{t-1} \\ \ddot{x}_{t-1} \end{bmatrix} + \begin{bmatrix} w_t \\ \dot{w}_t \\ \ddot{w}_t \end{bmatrix}$$

Method: State-Space Models

$$\text{transition model: } \overbrace{\boldsymbol{x}_t = \boldsymbol{Ax}_{t-1} + \boldsymbol{w}_t, \boldsymbol{w}_t: \boldsymbol{W} \sim \mathcal{N}(\boldsymbol{w}; \boldsymbol{0}, \boldsymbol{Q}_t)}^{\text{process error}}$$

$$\text{observation model: } \overbrace{\boldsymbol{y}_t = \boldsymbol{Cx}_t + \boldsymbol{v}_t, \boldsymbol{v}_t: \boldsymbol{V} \sim \mathcal{N}(\boldsymbol{v}; \boldsymbol{0}, \boldsymbol{R}_t)}^{\text{observation error}}$$

Inspector-Dependent Uncertainty

$$\text{observation model: } \overbrace{\boldsymbol{y}_t = \boldsymbol{Cx}_t + \boldsymbol{v}_t, \boldsymbol{v}_t: \boldsymbol{V}(I_i) \sim \mathcal{N}(\boldsymbol{v}; \boldsymbol{0}, \boldsymbol{R}_t(I_i))}^{\text{observation error}}, I_i \in [I_1, I_2, \dots, I_I] \quad \text{inspectors}$$

Proposed Degradation Model

State-Dependant Uncertainty



Figure 1. Transformation function $g(\cdot)$ with different n values.

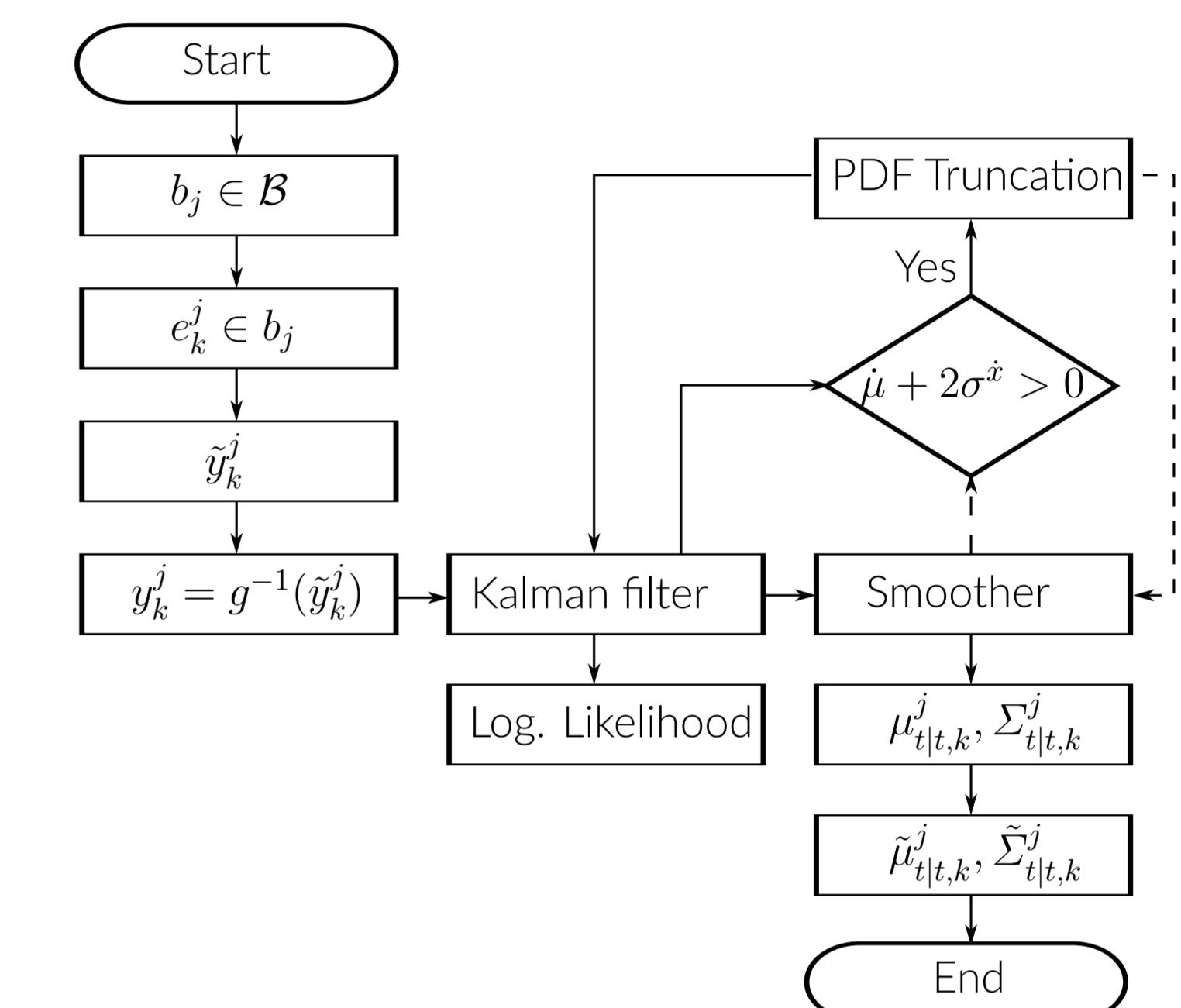


Figure 2. Flowchart of structural deterioration model

Results: Verification & Validation

Synthetic Data Analyses

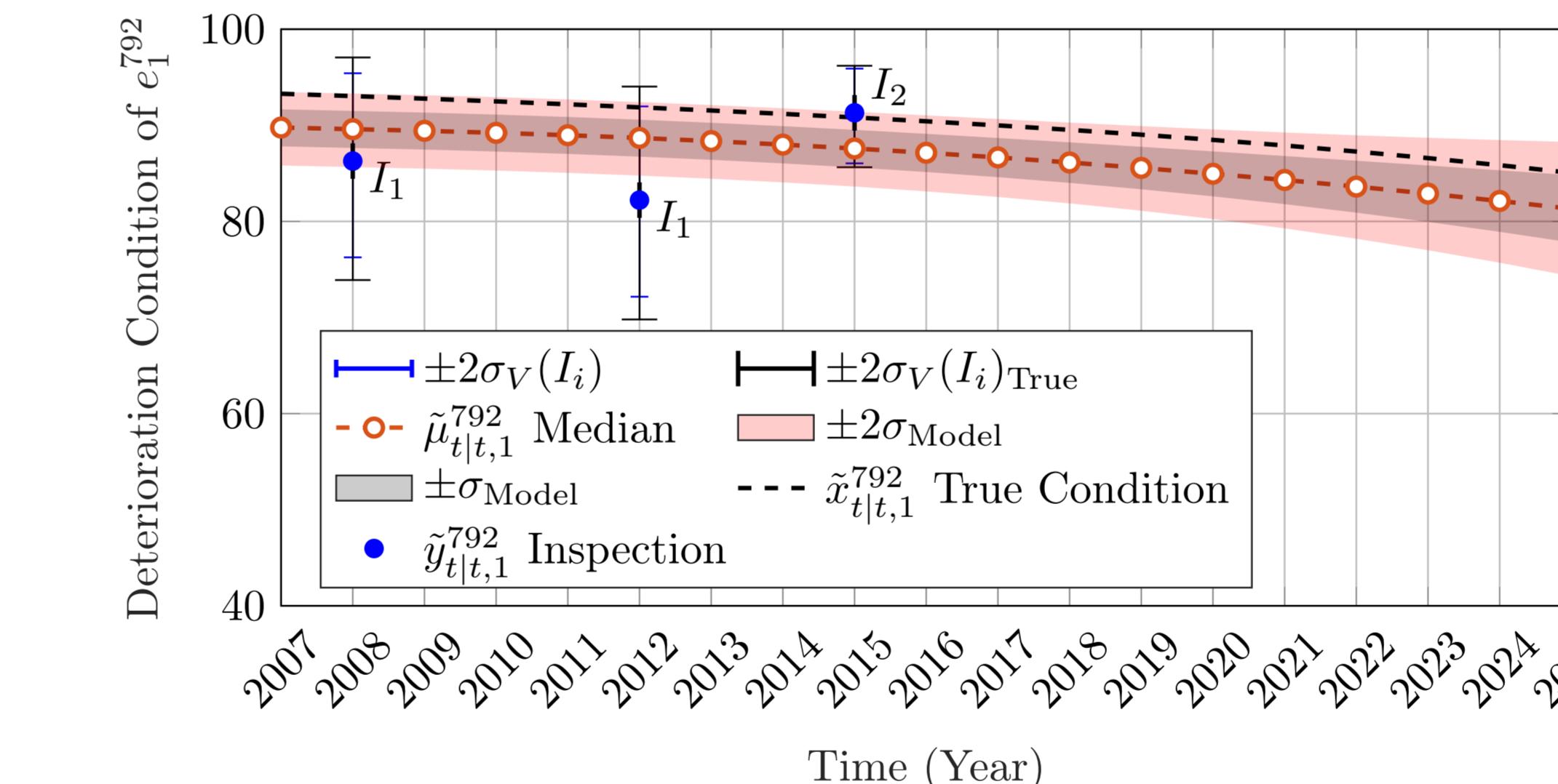


Figure 5. Condition deterioration analysis based on the observations \tilde{y}_1^{792} of the synthetic structural element e_1^{792} with error bars representing the Inspectors true (wide whiskers) & estimated (narrow whiskers) uncertainties.

Real Data Analyses

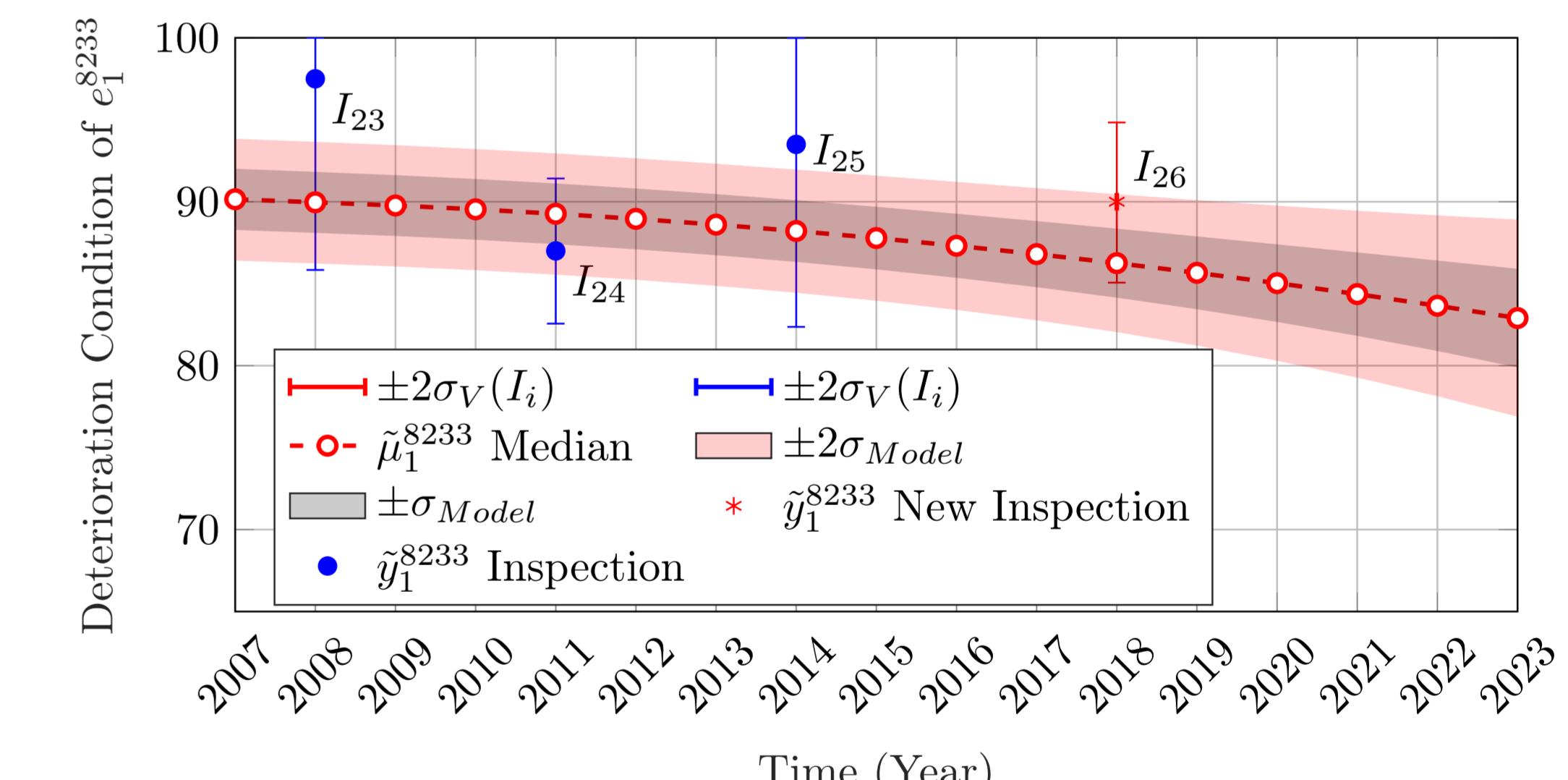


Figure 7. Condition deterioration analysis based on the observations \tilde{y}_1^{8233} of the structural element e_1^{8233} .

Example of Inspection Data for a Structural Element:

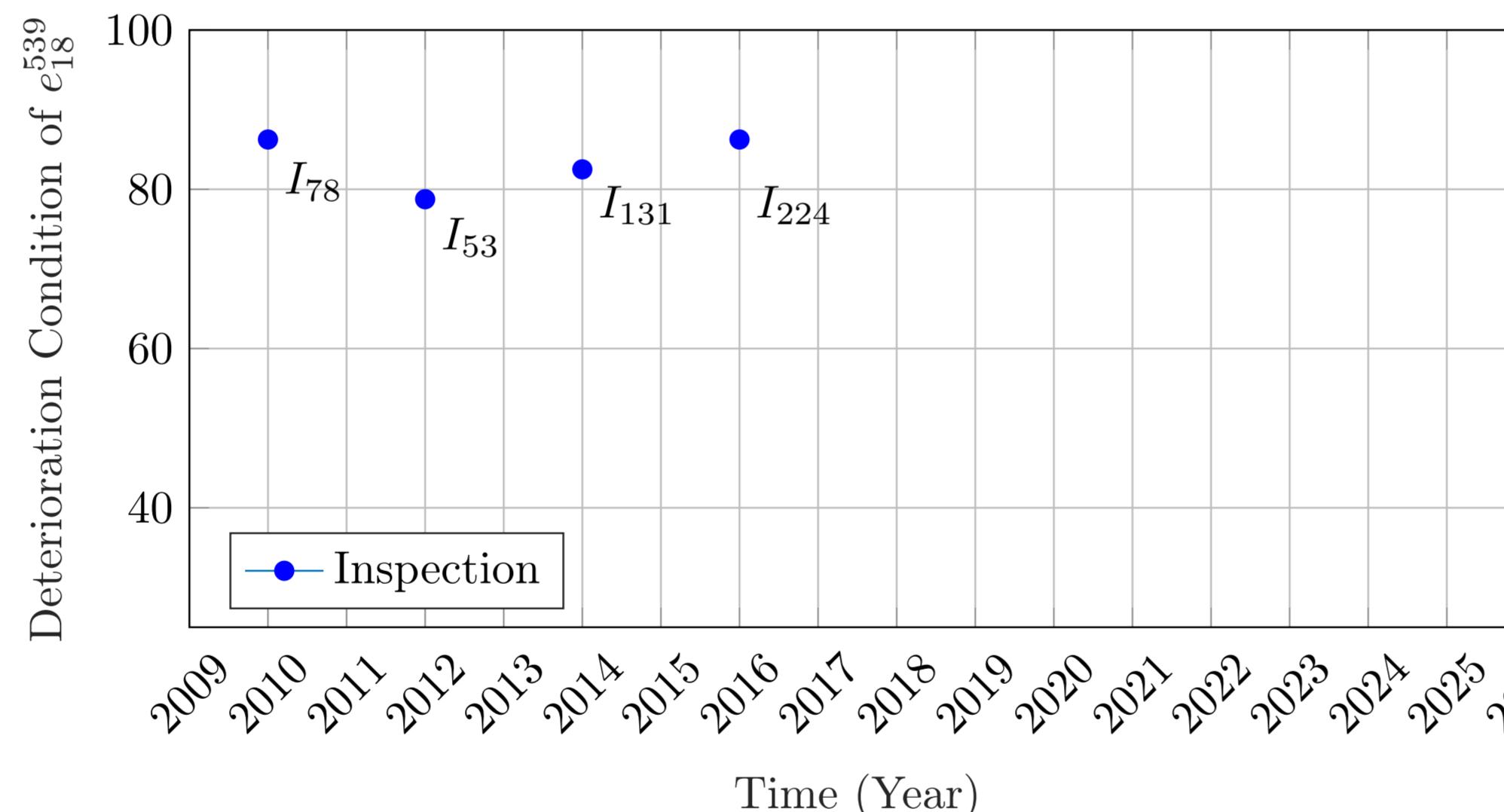


Figure 4. Inspections y_18^{539} of Structural Element e_18^{539}

Synthetic Inspection Data:



- # Structural Elements $E = 10827$.
- # Inspectors $I = 194$.

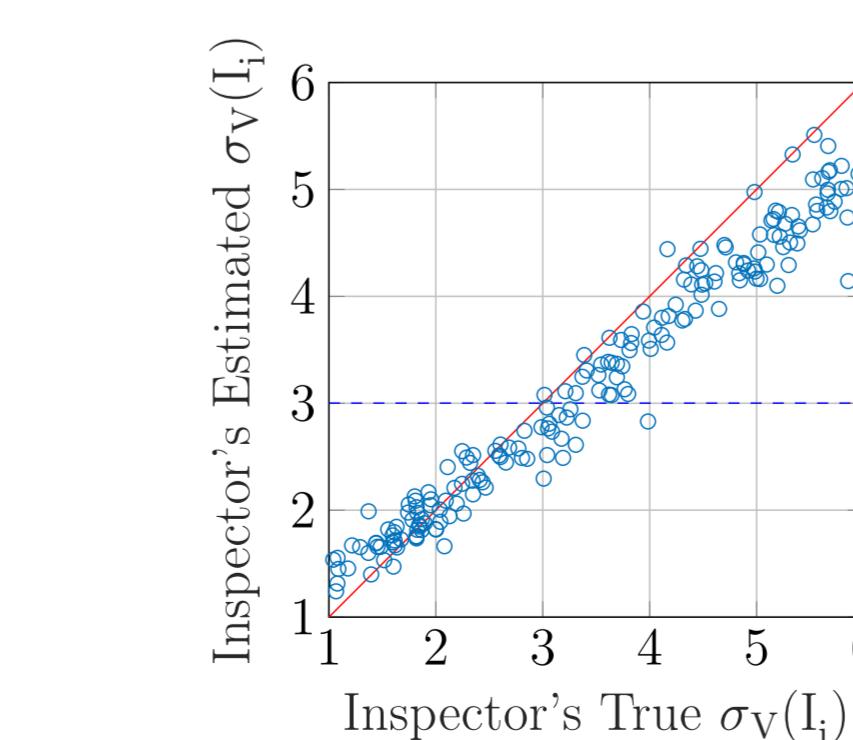


Figure 6. Scatter plot of inspectors true $\sigma_V(I_i)$ vs. estimated $\sigma_V(I_i)$ with a dashed line representing the initial value at the start of the optimization.

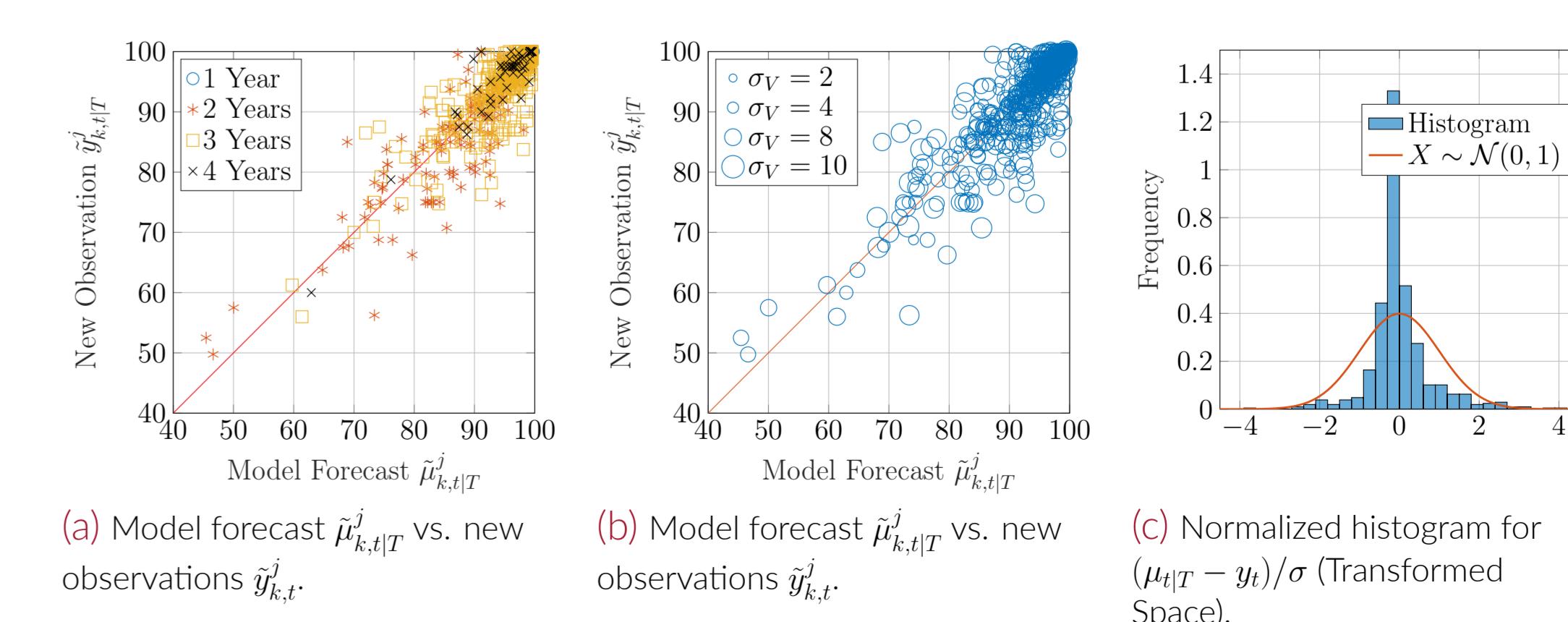


Figure 8. Deterioration condition validation for real structural elements.